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Non-linear control is a sub-division of control engineering which deals with the control of non-linear systems. The behaviour of a non-linear system cannot be described as a linear function of the state of that system or the input variables to that system. There exist several well-developed techniques for analysing non-linear feedback systems.

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The book is designed for universities that teach advance course in control systems. It presents the topics in an easy to understand manner with thorough explanations and detailed illustrations, to make students understand the basic underlying concepts. It presents the topics in an easy to understand manner with thorough explanations and detailed illustrations, so that students understand the basic underlying concepts. This book is organized into 5 chapters and appendices. The conventional and modern design concepts of continuous and discrete time control systems are presented in a very easiest and elaborative manner. The analysis and design of nonlinear control systems are included with clear explanations. Throughout the book, carefully chosen examples are presented so that the reader will have a clear understanding of the concepts discussed. Salient Features of the book: - Follows a cohesive approach to portray the basics. - Clear explanations of concepts with appropriate illustrations. - Step-by-step details to solved problems. - Exercises at the end of each chapter for self-practice - Bode plot, polar plot and root locus are presented in exact graph sheets with proper scale - Solutions to university questions for better scoring

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About the book... The book provides an integrated treatment of continuous-time and discrete-time systems for two courses at postgraduate level, or one course at undergraduate and one course at postgraduate level. It covers mainly two areas of modern control theory, namely; system theory, and multivariable and optimal control. The coverage of the former is quite exhaustive while that of latter is adequate with significant provision of the necessary topics that enables a research student to comprehend various technical papers. The stress is on interdisciplinary nature of the subject. Practical control problems from various engineering disciplines have been drawn to illustrate the potential concepts. Most of the theoretical results have been presented in a manner suitable for digital computer programming along with the necessary algorithms for numerical computations.

This book presents topics in an easy to understand manner with thorough explanations and detailed illustrations, to enable students to understand the basic underlying concepts. The fundamental concepts, graphs, design and analysis of control systems are presented in an elaborative manner. Throughout the book, carefully chosen examples are given so that the reader will have a clear understanding of the concepts.

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Designed as a textbook for undergraduate students pursuing courses in Electrical Engineering, Electrical and Electronics Engineering, Instrumentation and Control Engineering, and Electronics and Communication Engineering, this book explains the fundamental concepts and design principles of advanced control systems in an understandable manner. The book deals with the various types of state space modelling, characteristic equations, eigenvalues and eigenvectors including the design of the linear systems applying the pole placement technique. It provides step-by-step solutions to state equations and discusses the stability analysis and design of nonlinear control systems applying the phase plane technique, Routh's criteria, Bode plot, Nyquist plot, Lyapunov's and function methods. Furthermore, it also introduces the sampled-data control systems explaining the z-transforms and inverse z-transforms. The text is supported with a large number of illustrative examples and review questions to reinforce the student's understanding of the concepts.

Upper-level undergraduate text introduces aspects of optimal control theory: dynamic programming, Pontryagin's minimum principle, and numerical techniques for trajectory optimization. Numerous figures, tables. Solution guide available upon request. 1970 edition.



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Modern Control Systems, 12e, is ideal for an introductory undergraduate course in control systems for engineering students. Written to be equally useful for all engineering disciplines, this text is organized around the concept of control systems theory as it has been developed in the frequency and time domains. It provides coverage of classical control, employing root locus design, frequency and response design using Bode and Nyquist plots. It also covers modern control methods based on state variable models including pole placement design techniques with full-state feedback controllers and full-state observers. Many examples throughout give students ample opportunity to apply the theory to the design and analysis of control systems. Incorporates computer-aided design and analysis using MATLAB and LabVIEW MathScript.

Power System Analysis provides the basic fundamentals of power system analysis with detailed illustrations and explanations. Throughout the book, carefully chosen examples are given with a systematic approach to have a better understanding of the text discussed. It presents the topics of power system analysis including power system modeling, load

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flow studies, symmetrical and unsymmetrical fault analyses, stability analysis, etc. The book is principally designed as a self-study material for electrical engineering students.\* Cogent and lucid style of presentation.\* Clear explanations of concepts with appropriate illustrations.\* Examples with detailed explanations.\* Systematic, step-by-step approach to solved problems.\* Short-answer questions to recapitulate the basics.\* Exercises at the end of each chapter for self-practice.\* Solution to university questions for better scoring.

The Book Provides An Integrated Treatment Of Continuous-Time And Discrete-Time Systems For Two Courses At Undergraduate Level Or One Course At Postgraduate Level. The Stress Is On The Interdisciplinary Nature Of The Subject And Examples Have Been Drawn From Various Engineering Disciplines To Illustrate The Basic System Concepts. A Strong Emphasis Is Laid On Modeling Of Practical Systems Involving Hardware; Control Components Of A Wide Variety Are Comprehensively Covered. Time And Frequency Domain Techniques Of Analysis And Design Of Control Systems Have Been Exhaustively Treated And Their Interrelationship Established. Adequate Breadth And Depth Is Made Available For A Second Course. The Coverage Includes Digital Control Systems: Analysis, Stability And Classical Design; State Variables For Both Continuous-Time And Discrete-Time Systems; Observers And Pole-

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Placement Design; Liapunov Stability; Optimal Control; And Recent Advances In Control Systems: Adaptive Control, Fuzzy Logic Control, Neural Network Control. Salient Features \* State Variables Concept Introduced Early In Chapter 2 \* Examples And Problems Around Obsolete Technology Updated. New Examples Added \* Robotics Modeling And Control Included \* Pid Tuning Procedure Well Explained And Illustrated \* Robust Control Introduced In A Simple And Easily Understood Style \* State Variable Formulation And Design Simplified And Generalizations Built On Examples \* Digital Control; Both Classical And Modern Approaches, Covered In Depth \* A Chapter On Adaptive, Fuzzy Logic And Neural Network Control, Amenable To Undergraduate Level Use, Included \* An Appendix On Matlab With Examples From Time And Frequency Domain Analysis And Design, Included

The book is written for an undergraduate course on the Feedback Control Systems. It provides comprehensive explanation of theory and practice of control system engineering. It elaborates various aspects of time domain and frequency domain analysis and design of control systems. Each chapter starts with the background of the topic. Then it gives the conceptual knowledge about the topic dividing it in various sections and subsections. Each chapter provides the detailed explanation of the topic, practical examples and variety of solved

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problems. The explanations are given using very simple and lucid language. All the chapters are arranged in a specific sequence which helps to build the understanding of the subject in a logical fashion. The book starts with explaining the various types of control systems. Then it explains how to obtain the mathematical models of various types of systems such as electrical, mechanical, thermal and liquid level systems. Then the book includes good coverage of the block diagram and signal flow graph methods of representing the various systems and the reduction methods to obtain simple system from the analysis point of view. The book further illustrates the steady state and transient analysis of control systems. The book covers the fundamental knowledge of controllers used in practice to optimize the performance of the systems. The book emphasizes the detailed analysis of second order systems as these systems are common in practice and higher order systems can be approximated as second order systems. The book teaches the concept of stability and time domain stability analysis using Routh-Hurwitz method and root locus method. It further explains the fundamentals of frequency domain analysis of the systems including co-relation between time domain and frequency domain. The book gives very simple techniques for stability analysis of the systems in the frequency domain, using Bode plot, Polar plot and Nyquist plot methods. It also explores the concepts of compensation

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and design of the control systems in time domain and frequency domain. The classical approach loses the importance of initial conditions in the systems. Thus, the book provides the detailed explanation of modern approach of analysis which is the state variable analysis of the systems including methods of finding the state transition matrix, solution of state equation and the concepts of controllability and observability. The variety of solved examples is the feature of this book which helps to inculcate the knowledge of the design and analysis of the control systems in the students. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting.

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